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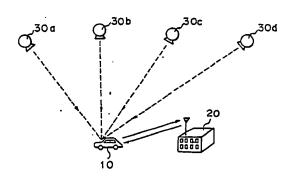
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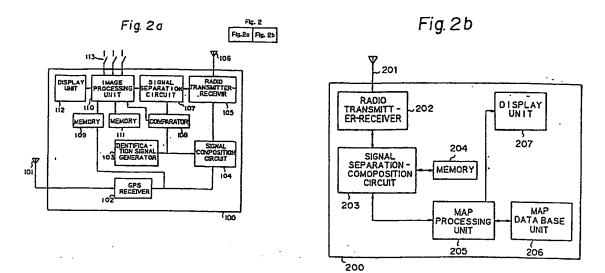
Mobile object navigation system.

(57) A mobile navigation system using a communication system between at least one mobile object (10) and a key station (20). The navigation system includes a unit (102) mounted on the mobile object for determining the position of the mobile object, and a unit (105) mounted on the mobile object for transmitting data representative of the determined position to the key station via the communication system. The navigation system further includes a data base unit (206) mounted in the key station for storing map data, a unit (205) mounted in the key station for deriving map data of an area including the position of the mobile object from the data base unit, in response to the transmitted position data, a unit (202) mounted in the key station for transmitting data including the derived map data to the mobile object via the communication system, and a unit (112) mounted on the mobile object for displaying a composite image composed of the position data of the mobile object and the map data, in response to the transmitted data from the key station.

Fig. I



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EUROPEAN SEARCH REPORT

EP 90 10 1019

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Category		th Indication, where appropriate, want passages		Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.5)
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Y	RECORD OF IEEE PLANS '88 POSITION LOCATION AND NAVIGATION SYMPOSIUM, "Navigation into the 21st century", Kissemmee, FL, 29th November - 2nd December 1988, pages 54-60, IEEE, New York, US; T. HUNTER et al.: "Land navigation and fleet management with GPS, LORAN, and dead reckoning sensors" "Page 54, right-hand column, line 12 - page 55, left-hand column, line 22; page 55, right-hand column, line 41 - page 56, right-hand column, line 20; page 57, right-hand column, line 20 - page 58, right-hand column, line 26; figures 1-3 *		er et al.: DRAN, and page lumn,	1-8	
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The present search report has been drawn up for all claims					
Place of search Date of completion of search			earch		Examiner
The Hague 13 May 91 CATEGORY OF CITED DOCUMENTS X: particularly relevant if taken alone Y: particularly relevant if combined with another document of the same catagory A: technological background O: non-written disclosure P: intermediate document T: theory or principle underlying the invention			HAFFNER R.D.R. E: earlier patent document, but published on, or after the filling date D: document cited in the application L: document cited for other reasons 8: member of the same patent family, corresponding document		